

Temposonics®

Magnetostrictive Linear Position Sensors

R-Series V

Brief Instructions



I AM THE NEW **V** GENERATION

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1. Introduction

1.1 Purpose and use of this manual

Before starting the operation of Temposonics® position sensors, read this documentation thoroughly and follow the safety information. Keep this manual for future reference!

The content of this technical documentation is intended to provide information on mounting, installation and commissioning by qualified automation personnel¹ or instructed service technicians who are familiar with the project planning and dealing with Temposonics® position sensors.

1.2 Used symbols and warnings

Warnings are intended for your personal safety and for avoidance of damage to the described product or connected devices. In this documentation, safety information and warnings to avoid danger that might affect the life and health of operating or service personnel or cause material damage are highlighted by the pictogram, defined below.

Symbol	Meaning
NOTICE	This symbol is used to point to situations that may lead to material damage, but not to personal injury.

- 1/ The term “qualified technical personnel” characterizes persons who
- are familiar with the safety concepts of automation technology applicable to the particular project and
 - are competent in the field of electromagnetic compatibility (EMC) or
 - have received adequate training for commissioning and service operations or
 - and are familiar with the operation of the device and know the information required for correct operation provided in the product documentation

2. Safety instructions

2.1 Intended use

This product may be used only for the applications defined under item 1 and only in conjunction with the third-party devices and components recommended or approved by MTS Sensors. As a prerequisite of proper and safe operation, the product requires correct transport, storage, mounting and commissioning and must be operated with utmost care.

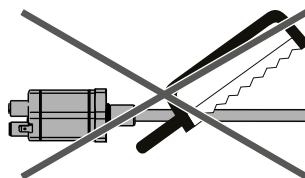
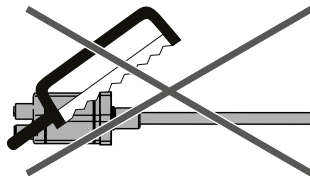
1. The sensor systems of all Temposonics® series are intended exclusively for measurement tasks encountered in industrial, commercial and laboratory applications. The sensors are considered as system accessories and must be connected to suitable evaluation electronics, e.g. a PLC, IPC, indicator or other electronic control unit.

2.2 Foreseeable misuse

Foreseeable misuse	Consequence
Wrong sensor connection	The sensor will not work properly or can be damaged
Operate the sensor out of the operating temperature range	No signal output The sensor can be damaged
Power supply is out of the defined range	Signal output is wrong / no signal output / the sensor can be damaged
Position measurement is influenced by an external magnetic field	Signal output is wrong
Cables are damaged	Short circuit – the sensor can be destroyed / sensor does not respond
Spacers are missing / are installed in the wrong order	Error in position measurement
Wrong connection of ground / shield	Signal output is disturbed The electronics can be damaged
Use of a magnet that is not certified by MTS Sensors	Error in position measurement

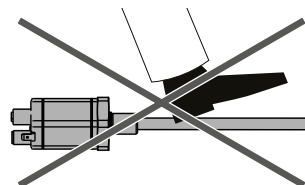
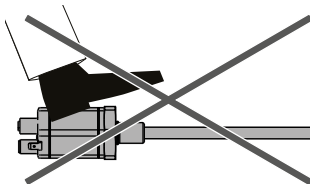
Do not alter the sensor.

→ The sensor might be damaged.



Do not step on the sensor.

→ The sensor might be damaged.



2.3 Installation, commissioning and operation

The position sensors must be used only in technically safe conditions. To maintain this condition and to ensure safe operation, installation, connection and service, work may be performed only by qualified technical personnel. If danger of injury to persons or of damage to operating equipment is caused by sensor failure or malfunction, additional safety measures such as plausibility checks, limit switches, EMERGENCY STOP systems, protective devices etc. are required. In the event of trouble, shut down the sensor and protect it against accidental operation.

Safety instructions for commissioning

To maintain the sensor operability, it is mandatory to follow the instructions given below.

1. Protect the sensor against mechanical damage during installation and operation.
2. Do not open or dismantle the sensor.
3. Connect the sensor very carefully and pay attention to the polarity of connections and power supply.
4. Use only approved power supplies.
5. Ensure the sensor is operating within the defined limits for supply voltage, environmental conditions, etc.
6. Check the function of the sensor regularly and provide documentation of the checks.
7. Before system switch-on, ensure that nobody's safety is jeopardized by starting machines.

2.4 Safety instructions for use in explosion-hazardous areas

The sensors are not suitable for operation in explosion-hazardous areas.

2.5 Warranty

MTS Sensors grants a warranty ² period for the Temposonics® position sensors and supplied accessories relating to material defects and faults that occur despite correct use in accordance with the intended application. The MTS Sensors obligation is limited to repair or replacement of any defective part of the unit. No warranty can be taken for defects that are due to improper use or above average stress of the product, as well as for wear parts. Under no circumstances will MTS Sensors accept liability in the event of offense against the warranty rules, no matter if these have been assured or expected, even in case of fault or negligence of the company. MTS Sensors explicitly excludes any further warranties. Neither the company's representatives, agents, dealers nor employees are authorized to increase or change the scope of warranty.

2.6 Return

For diagnostic purposes, the sensor can be returned to MTS Sensors or a repair facility explicitly authorized by MTS Sensors. Any shipment cost will be borne by the sender ². For a corresponding form, see detailed operation manual (available at: www.mtssensors.com).

2.7 Maintenance & removal

Further information about maintenance and removal is provided in the sensor specific operation manuals.

^{2/} See also applicable MTS Sensors sales and supply conditions, e.g. under www.mtssensors.com

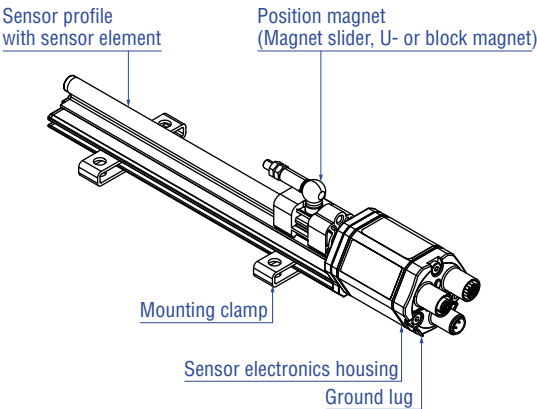
3. Identification

Nameplate (e.g. R-Series V Profinet)



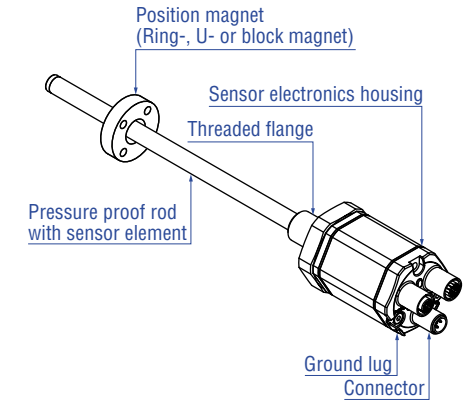
Approvals and certificates
You will find approvals and certificates in the sensor specific operation manuals.

3.1 Temposonics® RP5 (profile housing)



- Available outputs:**
- Profinet
 - EtherNet/IP™





3.2 Temposonics® RH5 (rod housing)



- Available outputs:**
- Profinet
 - EtherNet/IP™

Manuals, Software & 3D models
available at: www.mtssensors.com

4. Installation & mounting

 Ring magnet	For: RH <ul style="list-style-type: none"> • Rotationally symmetrical magnetic field
 U-magnet	For: RP & RH <ul style="list-style-type: none"> • The magnet can be lifted off (RP) • Height tolerances can be compensated
 Block magnet	For: RP & RH <ul style="list-style-type: none"> • The magnet can be lifted off • Height tolerances can be compensated
 Magnet slider	For: RP <ul style="list-style-type: none"> • The magnet is guided by the profile. • The distance between the magnet and the waveguide is strictly defined • Easy coupling via the ball joint

4.1 Magnet installation

Install the magnet using non-magnetic material for mounting device, screws, spacers etc.. The magnet must not grind on the sensor rod. Alignment errors are compensated via the air gap.

- Max. permissible surface pressure: 40 N/mm²
- Max. fastening torque for M4 screws: 1 Nm; use washers, if necessary

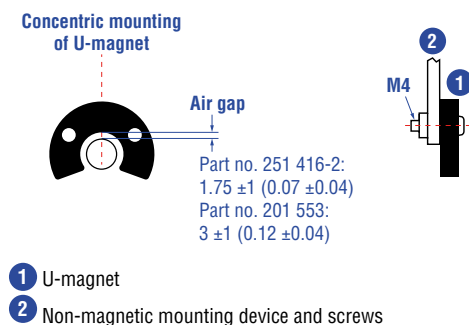
NOTICE

Mount the ring magnet and U-magnet concentrically. Mount the block magnet centrically.

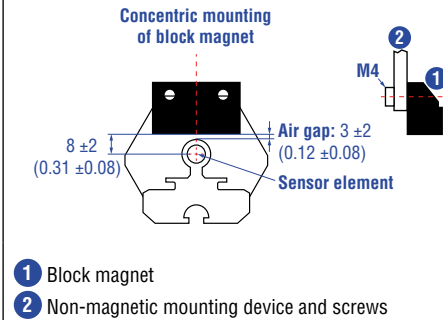
The maximum permissible air gap must not be exceeded.

Take care to mount the primary sensor axis in parallel to the magnet path in order to avoid damage to the carriage, magnet and sensor rod.

Concentric mounting of U-magnet

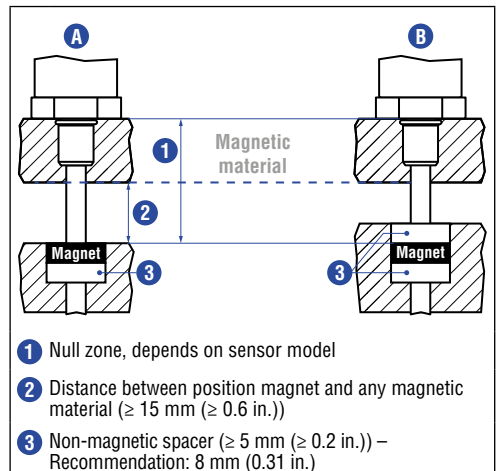


Centered mounting of block magnet



Magnet mounting with magnetic material

When using magnetic material the dimensions in the drawing beneath must be observed. If the position magnet is set further into the piston rod install another non-magnetic spacer above the magnet.

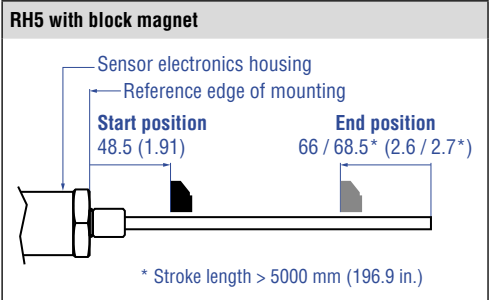
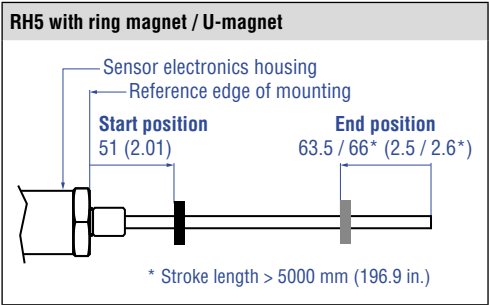
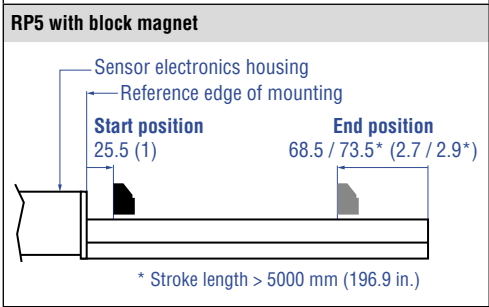
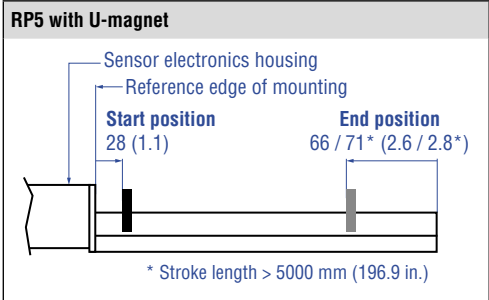
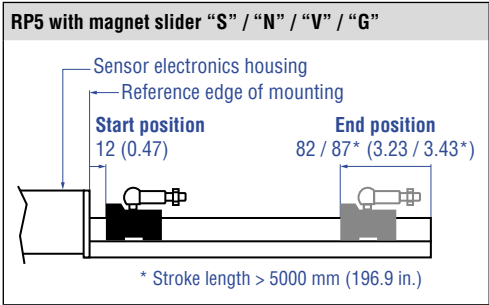


Sensors with stroke lengths ≥ 1 meter

Support horizontally installed sensors with a stroke length from 1 meter mechanically at the rod end. Without the use of a support, rod and position magnet may be damaged. A false measurement result is also possible. Longer rods require evenly distributed mechanical support over the entire length (e.g. part no. 561 481). Use an U-magnet for measurement.

Controlling design dimensions are in millimeters and measurements in () are in inches

4.2 Mounting dimensions



NOTICE

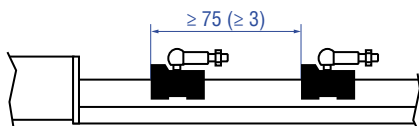
- The sensor can be operated in any orientation.
- On all sensors, use only the active measurement stroke, which is between the start and end positions. The magnet may move beyond these positions.

4.3 Multi-position measurement distances

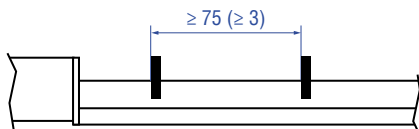
Multi-position measurements are possible depending on the output. It is possible to measure up to 30 positions positions and their velocities.

The stroke length of the sensor influences the maximum number of magnets.

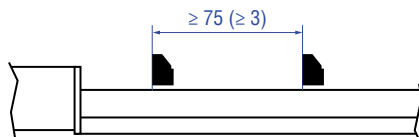
RP5 with magnet sliders “S” / “N” / “V” / “G”



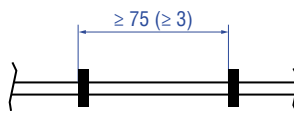
RP5 with U-magnets



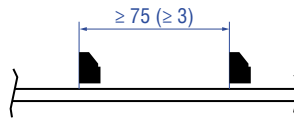
RP5 with block magnets



RH5 with ring magnets / U-magnets



RH5 with block magnets



NOTICE

Use magnets of the same type for multi-position measurement, e.g. 2 × U-magnets (part no. 251 416-2).

5. Electrical connections & LED status

Placement of installation and cabling have decisive influence on the sensor's electromagnetic compatibility (EMC). Hence correct installation of this active electronic system and the EMC of the entire system must be ensured by using suitable metal connectors, shielded cables and grounding. Overvoltages or faulty connections can damage its electronics despite protection against wrong polarity.

NOTICE

- 1. Do not mount the sensors in the area of strong magnetic or electric noise fields.
- 2. Never connect / disconnect the sensor when voltage is applied.

Instructions for connection

- Use low-resistant twisted pair and shielded cables. Connect the shield to ground externally via the controller equipment.
- Keep control and signal cables separate from power cables and sufficiently far away from motor cables, frequency inverters, valve lines, relays, etc..
- Use only connectors with metal housing and connect the shielding to the connector housing.
- Keep the connection surface at both shielding ends as large as possible. Connect the cable clamps to function as a ground.
- Keep all non-shielded leads as short as possible.
- Keep the earth connection as short as possible with a large cross section. Avoid ground loops.
- With potential differences between machine and electronics earth connections, no compensating currents are allowed to flow across the cable shielding.

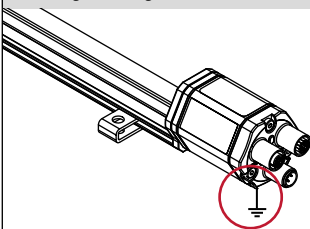
Recommendation:

- Install potential compensating leads with large cross section, or use cables with separate double shielding, and connect only one end of the shield.
- Use only stabilized power supplies in compliance with the specified electrical ratings.

Grounding of profile and rod sensors

Connect the sensor electronics housing to machine ground. Ground sensor types RP5 and RH5 via ground lug. In addition you can ground the sensor type RH5 via thread.


Sensor grounding




5.1 Profinet


D58

Signal

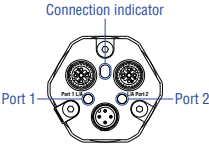
Port 1 – M12 female connector (D-coded)	Pin	Function
 View on sensor	1	Tx (+)
	2	Rx (+)
	3	Tx (-)
	4	Rx (-)
	5	Not connected

Port 2 – M12 female connector (D-coded)	Pin	Function
 View on sensor	1	Tx (+)
	2	Rx (+)
	3	Tx (-)
	4	Rx (-)
	5	Not connected

Power supply

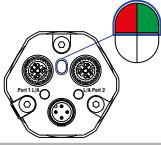
M12 male connector (A-coded)	Pin	Function
 View on sensor	1	12...30 VDC (±20 %)
	2	Not connected
	3	DC Ground (0 V)
	4	Not connected

Profinet RT & IRT LED status



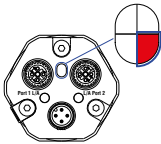
Connection indicator

Device status LED



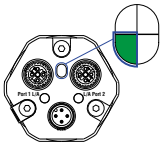
Green	Red	Information
● ON	○ OFF	No Error
○ OFF	● ON	Operating voltage out of range or magnet error

Bus status LED



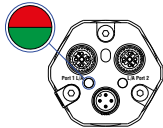
Red	Information
○ OFF	No Error
● ON	No connection to controller
● Flashing	Parameterization error

LED for sensor identification



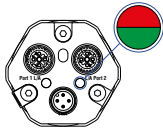
Green	Information
● Flashing	Sensor identification activated

Port 1 L/A






Green	Red	Information
● ON	○ OFF	Connection to the next network node established
● ON	● Flashing	Connection to the next network device established & communication active




Port 2 L/A



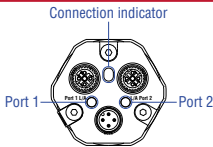
Green	Red	Information
● ON	○ OFF	Connection to the next network node established
● ON	● Flashing	Connection to the next network device established & communication active

5.2 EtherNet/IP™

D56		
Ports		
Port 1 – M12 female connector (D-coded)	Pin	Function
 View on sensor	1	Tx (+)
	2	Rx (+)
	3	Tx (-)
	4	Rx (-)
	5	Not connected
Port 2 – M12 female connector (D-coded)	Pin	Function
 View on sensor	1	Tx (+)
	2	Rx (+)
	3	Tx (-)
	4	Rx (-)
	5	Not connected
Power supply		
M8 male connector	Pin	Function
 View on sensor	1	12...30 VDC (±20 %)
	2	Not connected
	3	DC Ground (0 V)
	4	Not connected

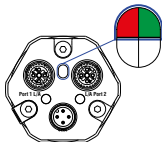
D58		
Signal		
Port 1 – M12 female connector (D-coded)	Pin	Function
 View on sensor	1	Tx (+)
	2	Rx (+)
	3	Tx (-)
	4	Rx (-)
	5	Not connected
Port 2 – M12 female connector (D-coded)	Pin	Function
 View on sensor	1	Tx (+)
	2	Rx (+)
	3	Tx (-)
	4	Rx (-)
	5	Not connected
Power supply		
M12 male connector (A-coded)	Pin	Function
 View on sensor	1	12...30 VDC (±20 %)
	2	Not connected
	3	DC Ground (0 V)
	4	Not connected

EtherNet/IP™ LED status



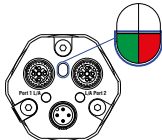
Connection indicator

Module status LED



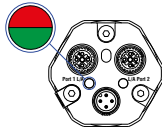
Green	Red	Information
● ON	○ OFF	IP address configured
● Flashing	○ OFF	IP address not configured
○ OFF	● Flashing	Duplicate of IP address recognized

Network status LED



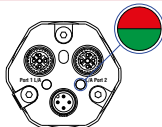
Green	Red	Information
● ON	○ OFF	Connection established
● Flashing	○ OFF	No connection
○ OFF	● ON	Unrecoverable error
○ OFF	● Flashing	Recoverable error

Port 1 L/A (IN)



Green	Red	Information
● ON	○ OFF	LINK activity on port 1
● Flickers	○ OFF	Data transfer on port 1
○ OFF	● ON	No magnet / Wrong quantity of magnets

Port 2 L/A (OUT)



Green	Red	Information
● ON	○ OFF	LINK activity on port 2
● Flickers	○ OFF	Data transfer on port 2

Notes

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Notes

[illegible]

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