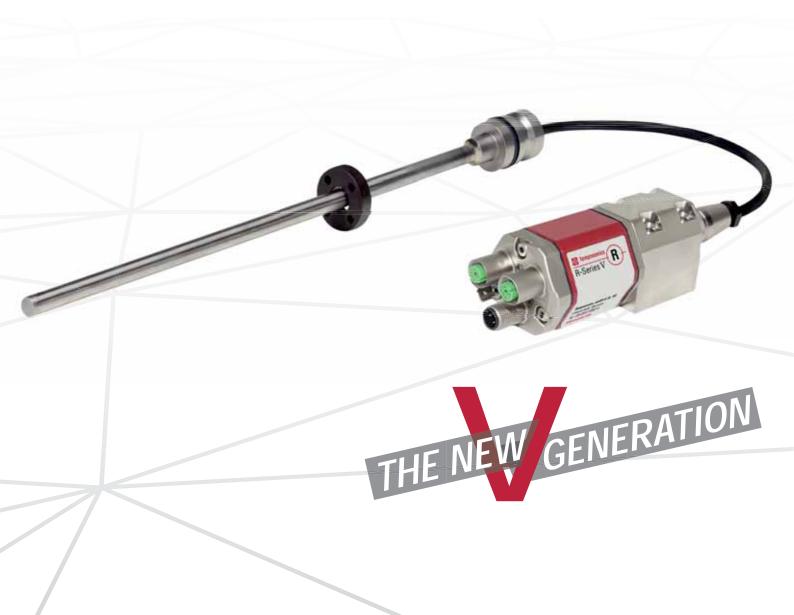


Data Sheet

R-Series V RDV EtherNet/IP™

Magnetostrictive Linear Position Sensors

- Space-saving installation due to detached sensor electronics housing
- Backwards compatible with RD4 generation
- All advantages of the R-Series V



MEASURING TECHNOLOGY

The absolute, linear position sensors provided by Temposonics rely on the company's proprietary magnetostrictive technology, which can determine position with a high level of precision and robustness. Each Temposonics position sensor consists of a ferromagnetic waveguide, a position magnet, a strain pulse converter and a supporting electronics. The magnet, connected to the object in motion in the application, generates a magnetic field at its location on the waveguide. A short current pulse is applied to the waveguide. This creates a momentary radial magnetic field and torsional strain on the waveguide. The momentary interaction of the magnetic fields releases a torsional strain pulse that propagates the length of the waveguide. When the ultrasonic wave reaches the beginning of the waveguide it is converted into an electrical signal. Since the speed of the ultrasonic wave in the waveguide is precisely known, the time required to receive the return signal can be converted into a linear position measurement with both high accuracy and repeatability.

R-SERIES V RDV EtherNet/IP™

The Temposonics® R-Series V brings very powerful sensor performance to meet the many demands of your application. The sensor RDV is the version of the R-Series V with a detached sensor electronics. The main advantages of the version RDV are:



Space-saving installation

The detached sensor electronics allow space-saving installation of the compact measuring rod.



R-Series V platform

The detached sensor electronics is based on the R-Series V and offers all advantages of the innovative series.



Backwards compatible

Mechanically and electrically, the sensors are backwards compatible with the RD4. This means that the sensor rod or the sensor electronics can be replaced without any problems.



Protection of the sensor electronics

By separating the robust sensor rod from the complex evaluation electronics, improved protection against process influences can be realized.

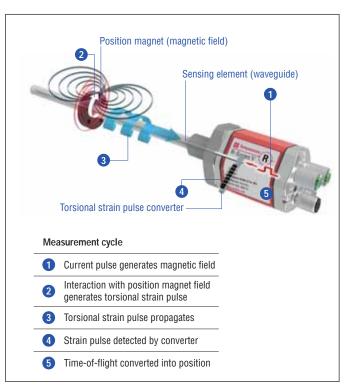


Fig. 1: Time-of-flight based magnetostrictive position sensing principle

In addition the R-Series V EtherNet/IP™ scores with the following features:



20 positions simultaneously

The R-Series V EtherNet/IP $^{\text{TM}}$ can detect and report the position and velocity of up to 20 magnets simultaneously.



R-Series V EtherNet/IP™

The sensor supports DLR. The DLR capability provides a fault-tolerant network so that the sensor can be used in ring connection topologies when reliable continuous system operation is required.

All settings under control with the sensor assistants for the R-Series V The TempoLink® and the TempoGate® smart assistants support you in setup and diagnostics of the R-Series V. For more information of these assistants please see the data sheets:

 TempoLink® smart assistant (<u>Document part number: 552070</u>)

 TempoGate[®] smart assistant (<u>Document part number: 552110</u>)



TECHNICAL DATA

Output								
Interface	EtherNet/IP™							
		nrof	ilo with CID CynoIM	and	DI D canabilities			
Data protocol		Encoder CIP device profile with CIP Sync™ and DLR capabilities						
Data transmission rate	100 MBit/s (maximu	,	0: "					
Measured value								
Measurement parameters								
Resolution: Position		1500 µm (selectable)						
Cycle time	Stroke length		≤ 2000 mm		≤ 4800 mm	_	5080 mm	
Linearity deviation 1.2	Cycle time 1.0 ms 2.0 ms 3.0 ms				3.0 ms			
Linearity deviation 1, 2	Stroke length Linearity deviation	≤ 500 mm ion ≤ ±50 μm			> 500 mm < 0.01 % F.S.			
	Optional internal linearity: Linearity tolerance (Applies for the first magnet for multi-position measurement)							
	Stroke length					01200 mm		
	typical	± 1	5 μm	± 2	0 μm	_	5 μm	
	maximum	± 2	5 μm	± 3	0 μm	± 50 μm		
Repeatability	< ±0.001 % F.S. (mi	nim	ım ±2.5 μm) typica	I				
Hysteresis	< 4 µm typical	< 4 µm typical						
Temperature coefficient	< 15 ppm/K typical							
Operating conditions								
Operating temperature	-40+85 °C (-40.	+18	35 °F)					
Humidity	90 % relative humidity, no condensation							
Ingress protection	Sensor electronics IP67 (with professional mounted housing and connectors)							
	Measuring rod with connecting cable for side cable entry IP65 Measuring rod with single wires and flat connector with bottom cable entry IP30							
Shock test	100 g/11 ms, IEC standard 60068-2-27							
Vibration test	10 g/102000 Hz, IEC standard 60068-2-6 (excluding resonant frequencies)							
EMC test	Electromagnetic emission according to EN 61000-6-3 Electromagnetic immunity according to EN 61000-6-2 The RDV sensors fulfill the requirements of the EMC directives 2014/30/EU, UKSI 2016 No. 1091 and TR CU 020/2011 under the condition of an EMC-compliant installation. ³							
Operating pressure	350 bar (5076 psi)/700 bar (10,153 psi) peak (at 10 × 1 min) for sensor rod							
Magnet movement velocity	Any							
Design/Material								
Sensor electronics housing	Aluminum (painted)	, zin	c die cast					
Sensor rod with flange	Stainless steel 1.43	Stainless steel 1.4301 (AISI 304)						
RoHS compliance	The used materials are compliant with the requirements of EU Directive 2011/65/EU and EU Regulation 2015/863 as well as UKSI 2022 No. 622							
Stroke length 252540 mm (1100 in.) for pressure-fit flange »S« 255080 mm (1200 in.) for all threaded flanges								
Mechanical mounting								
Mounting position	·							
Mounting instruction	Please consult the technical drawings on page 4 and the operation manual (document number: 551971)							
Electrical connection								
Connection type	2 × M12 female connectors (5 pin), 1 × M12 male connector (4 pin) 2 × M12 female connectors (5 pin), 1 × M8 male connector (4 pin)							
Operating voltage	+1230 VDC ±20 % (9.636 VDC)							
Power consumption	Less than 4 W typical							
Dielectric strength	500 VDC (DC ground to machine ground)							
Polarity protection	Up to –36 VDC							
Overvoltage protection	·							
•								

With position magnet # 251 416-2
 For rod style »S« the linearity deviation can be higher in the first 30 mm (1.2 in.) of stroke length
 The cable between the sensor element and the electronic housing must be mounted in an appropriately shielded environment.

TECHNICAL DRAWING

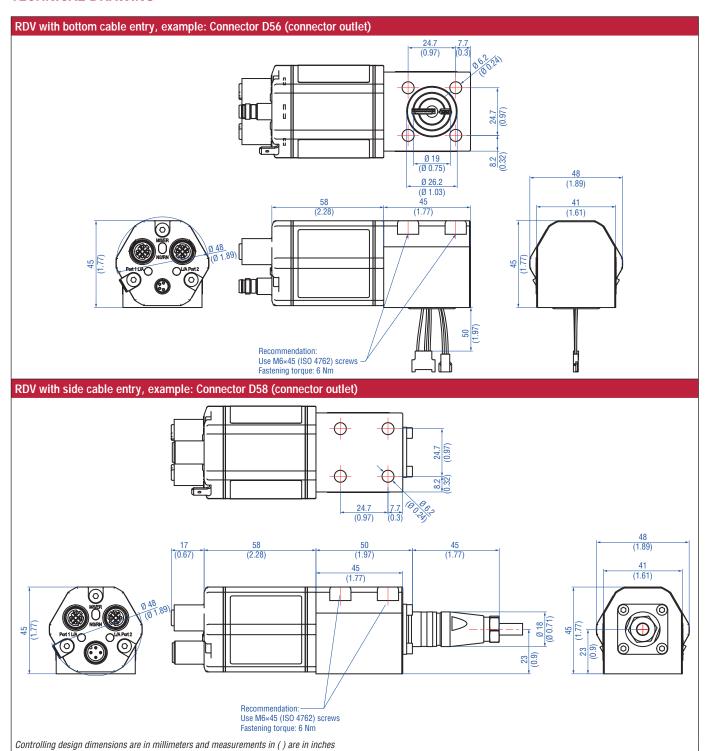


Fig. 2: Temposonics* RDV sensor electronics housing

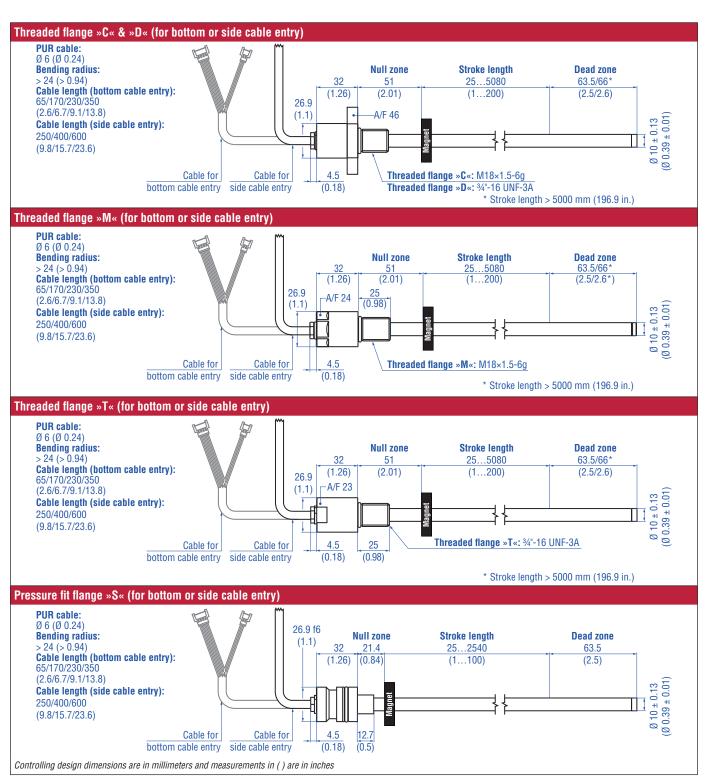


Fig. 3: Temposonics® RDV flange types

CONNECTOR WIRING

D58						
Port 1 – Signal						
M12 female connector (D-coded)	Pin	Function				
	1	Tx (+)				
$4\bigcirc 2$	2	Rx (+)				
3.	3	Tx (-)				
View on sensor	4	Rx (-)				
Port 2 – Signal						
M12 female connector (D-coded)	Pin	Function				
	1	Tx (+)				
2 (4)	2	Rx (+)				
1	3	Tx (-)				
View on sensor	4	Rx (-)				
Power supply	Power supply					
M12 male connector (A-coded)	Pin	Function				
	1	+1230 VDC (±20 %)				
(°°)	2	Not connected				
	3	DC Ground (0 V)				
View on sensor	4	Not connected				

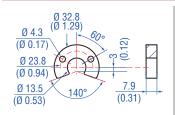
Fig. 4: Connector wiring D58

D56					
Port 1 – Signal					
M12 female connector (D-coded)	Pin	Function			
	1	Tx (+)			
$4\bigcirc 2$	2	Rx (+)			
3	3	Tx (-)			
View on sensor	4	Rx (-)			
Port 2 – Signal					
M12 female connector (D-coded)	Pin	Function			
	1	Tx (+)			
2 (4)	2	Rx (+)			
1	3	Tx (-)			
View on sensor	4	Rx (-)			
Power supply					
M8 male connector	Pin	Function			
	1	+1230 VDC (±20 %)			
6 9	2	Not connected			
View on sensor	3	DC Ground (0 V)			
VIEW UII SEIISUI	4	Not connected			

Fig. 5: Connector wiring D56

FREQUENTLY ORDERED ACCESSORIES - Additional options available in our Accessories Guide 1 551444

Position magnets



Ø 4.3 (Ø 0.17) Ø 13.5 (Ø 0.53) (0.31)

Ø 25.4 (Ø 1) Ø 13.5 $(\emptyset \ 0.53)$ (0.31)

Ø 17.4 (Ø 0.69) Ø 13.5 (0.53)(0.31)

U-magnet OD33 Part no. 251416-2

Material: PA ferrite GF20 Weight: Approx. 11 g Surface pressure: Max. 40 N/mm² Fastening torque for M4 screws: 1 Nm Operating temperature: -40...+105 °C (-40...+221 °F)

Marked version for sensors with internal linearization: Part no. 254226

Ring magnet OD33 Part no. 201 542-2

Material: PA ferrite GF20 Weight: Approx. 14 g Surface pressure: Max. 40 N/mm² Fastening torque for M4 screws: 1 Nm Operating temperature: -40...+105 °C (-40...+221 °F)

Marked version for sensors with internal linearization: Part no. 253 620

Ring magnet OD25.4 Part no. 400 533

Material: PA ferrite Weight: Approx. 10 g Surface pressure: Max. 40 N/mm² Operating temperature: -40...+105 °C (-40...+221 °F)

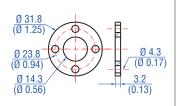
Marked version for sensors with internal linearization: Part no. 253 621

Ring magnet OD17.4 Part no. 401 032

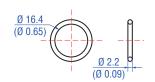
Material: PA neobond Weight: Approx. 5 g Surface pressure: Max. 20 N/mm² Operating temperature: -40...+105 °C (-40...+221 °F)

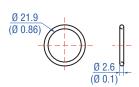
Magnet spacer

0-rings









Magnet spacer Part no. 400 633

Material: Aluminum Weight: Approx. 5 g Surface pressure: Max. 20 N/mm² Fastening torque for M4 screws: 1 Nm

O-ring for threaded flange M18×1.5-6g Part no. 401 133

Material: Fluoroelastomer Durometer: 75 ± 5 Shore A Operating temperature: -40...+204 °C (-40...+400 °F)

O-ring for threaded flange 34"-16 UNF-3A Part no. 560 315

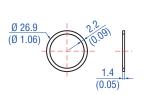
Material: Fluoroelastomer Durometer: 75 ± 5 Shore A Operating temperature: -40...+204 °C (-40...+400 °F)

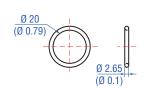
O-ring for pressure fit flange Ø 26.9 mm Part no. 560 705

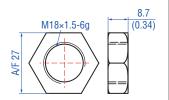
Material: Nitrile rubber Operating temperature: -53...+107 °C (-65...+225 °F)

O-rings

Mounting accessories









Back-up ring for pressure fit flange Ø 26.9 mm Part no. 560 629

Material: Polymyte Durometer: 90 Shore A

O-ring for mounting block with bottom Part no. 561 435

Material: FKM Durometer: 80± 5 Shore A Operating temperature: -15...+200 °C (5...+392 °F)

Hex jam nut M18×1.5-6g Part no. 500 018

Material: Steel, zinc plated

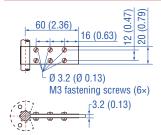
Hex jam nut 3/4"-16 UNF-3A Part no. 500 015

Material: Steel, zinc plated

Temposonics® R-Series V RDV EtherNet/IP™

Data Sheet

Mounting accessory

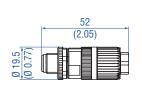


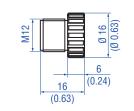
Fixing clip Part no. 561 481

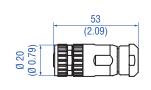
Application: Used to secure sensor rods (Ø 10 mm (Ø 0.39 in.)) when using an U-magnet or block magnet Material: Brass, non-magnetic

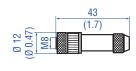
Cable connectors* - Signal

Cable connectors* - Power









M12 D-coded male connector (4 pin), straight Part no. 370 523

Material: Zinc nickel-plated Termination: Insulation-displacement Cable Ø: 5.5...7.2 mm (0.2...0.28 in.) –25...+85 °C (–13...+185 °F)

Wire: 24 AWG - 22 AWG Operating temperature: Ingress protection: IP65 / IP67 (correctly fitted) Fastening torque: 0.6 Nm

M12 connector end cap Part no. 370 537

Female connectors M12 should be covered by this protective cap Material: Brass nickel-plated Ingress protection: IP67 (correctly fitted) Cable Ø: 4...8 mm (0.16...0.31 in.) Fastening torque: 0.39...0.49 Nm

M12 A-coded female connector (4 pin/5 pin), straight Part no. 370 677

Material: GD-Zn, Ni Termination: Screw Contact insert: CuZn Wire: 1.5 mm² Operating temperature: -30...+85 °C (-22...+185 °F) Ingress protection: IP67 (correctly fitted)

Fastening torque: 0.6 Nm

M8 female connector (4 pin), straight Part no. 370 504

Material: CuZn nickel plated Termination: Solder Cable Ø: 3.5...5 mm (0.14...0.28 in.) Wire: 0.25 mm² Operating temperature: -40...+85 °C (-40...+185 °F) Ingress protection: IP67 (correctly fitted) Fastening torque: 0.5 Nm

Cables Cable sets









PUR signal cable Part no. 530 125

Material: PUR jacket; green Features: Cat 5, highly flexible, halogen free, suitable for drag chains, mostly oil & flame resistant Cable Ø: 6.5 mm (0.26 in.) Cross section: $2 \times 2 \times 0.35 \text{ mm}^2$ (22 AWG) Bending radius: 5 × D (fixed installation) Operating temperature: -20...+60 °C (-4...+140 °F)

PVC power cable Part no. 530 108

Material: PVC jacket; gray Features: Shielded, flexible. mostly flame resistant Cable Ø: 4.9 mm (0.19 in.) Cross section: $3 \times 0.34 \text{ m/m}^2$ Bending radius: 5 × D (fixed installation) Operating temperature: -30...+80 °C (-22...+176 °F)

Signal cable with M12 D-coded male connector (4 pin), straight - M12 D-coded, male connector (4 pin), straight Part no. 530 064

Material: PUR jacket; green Features: Cat 5e Cable length: 5 m (16.4 ft) Cable Ø: 6.5 mm (0.26 in.) Ingress protection: IP65, ÍP67, IP68 (correctly fitted) Operating temperature: -30...+70 °C (-22...+158 °F)

Signal cable with M12 D-coded male connector (4 pin), straight – RJ45 male connector, straight Part no. 530 065

Material: PUR jacket; green Features: Cat 5e Cable length: 5 m (16.4 ft) Cable Ø: 6.5 mm (0.26 in.) Ingress protection M12 connector: IP67 (correctly fitted) Ingress protection RJ45 connector: IP20 (correctly fitted) Operating temperature: -30...+70 °C (-22...+158 °F)

^{*/} Follow the manufacturer's mounting instructions Controlling design dimensions are in millimeters and measurements in () are in inches Color of connectors and cable jacket may change. Colors of the cores and technical properties remain unchanged.

Cable sets Programming tools Power cable with M8 female connector Power cable with M12 A-coded female TempoLink® kit for Temposonics® TempoGate® smart assistant for connector (5 pin), straight - pigtail Temposonics® R-Series V (4 pin), straight - pigtail R-Series V Part no. 530 066 (5 m (16.4 ft.)) Part no. 370 673 Part no. TL-1-0-EM08 (D56) Part no. TG-C-0-Dxx Part no. 530 096 (10 m (32.8 ft.)) Part no. TL-1-0-EM12 (D58) (xx indicates the number of R-Serie V Part no. 530 093 (15 m (49.2 ft.)) sensors that can be connected (even numbers only)) Material: PUR jacket; gray Material: PUR jacket; black • Connect wirelessly via Wi-Fi enabled · OPC UA server for diagnostics of the Features: Shielded Features: Shielded device or via USB with the diagnostic R-Series V Cable Ø: 5 mm (0.2 in.) Cable length: 5 m (16.4 ft) tool • For installation in the control cabinet Ingress protection: IP67 (correctly fitted) • Connection via LAN and Wi-Fi Operating temperature: · Simple connectivity to the sensor -40...+90 °C (-40...+194 °F) Operating temperature: via 24 VDC power line (permissible • See data sheet "TempoGate® smart -25...+80 °C (-13...+176 °F) cable length: 30 m) assistant" document part no .: User friendly interface for mobile 552110) for further information devices and desktop computers See data sheet "TempoLink® smart assistant" (document part no.: 552070) for further information

ORDER CODE

1 2 3	4							18 19	
R D V					D 5	1	U	2	1
а	b	С	d	е	f	g		h	

a Design

R D V Detached sensor electronics "Classic"

b Design

- C Threaded flange M18×1.5-6g (A/F 46)
- D Threaded flange 3/4"-16 UNF-3A (A/F 46)
- M Threaded flange M18×1.5-6g (A/F 24)
- Pressure fit flange Ø 26.9 mm f6
- T Threaded flange 3/4"-16 UNF-3A (A/F 23)

c Mechanical options

For side cable entry

- A PUR cable with M16 connector, 250 mm length
- B PUR cable with M16 connector, 400 mm length
- C PUR cable with M16 connector, 600 mm length

For bottom cable entry

- 2 | Single wires with flat connector, 65 mm length
- Single wires with flat connector, 170 mm length
- Single wires with flat connector, 230 mm length
- Single wires with flat connector, 350 mm length

d Stroke length

X X X X M Flange »S«: 0025...2540 mm Flange »C«, »D«, »M«, »T«: 0025...5080 mm

Stroke length (mm)	Ordering steps	
25 500 mm	5 mm	
500 750 mm	10 mm	
7501000 mm	25 mm	
10002500 mm	50 mm	
25005080 mm	100 mm	

X X X X U Flange »S«: 001.0...100.0 in. Flange »C«, »D«, »M«, »T«: 001.0...200.0 in.

Stroke length (in.)	Ordering steps
1 20 in.	0.2 in.
20 30 in.	0.4 in.
30 40 in.	1.0 in.
40100 in.	2.0 in.
100200 in.	4.0 in.

Non standard stroke lengths are available; must be encoded in 5 mm/0.1 in. increments

e Number of magnets

X X 01...20 position(s) (1...20 magnet(s))

Connection type

- 5 6 2×M12 female connectors (D-coded), 1 × M8 male connector
- 2×M12 female connectors (D-coded), 1 × M12 male connector (A-coded)
- g System
- 1 Standard

h Output

- 1 EtherNet/IP™, position and velocity (1...20 magnet(s))
- 1 EtherNet/IP™, position and velocity, internal linearization (1...20 magnet(s))

NOTICE

- Specify number of magnets for your application and order the magnets separately.
- The number of magnets is limited by the stroke length. The minimum allowed distance between magnets (i.e. front face of one to the front face of the next one) is 75 mm (3 in.).
- Use magnets of the same type for multi-position measurement.
- If the option for internal linearization (U211) in h "Output" is chosen, select a suitable magnet.

DELIVERY



Sensor, O-ring RDV-S:

Sensor, O-ring, back-up ring

Accessories have to be ordered separately.

Manuals, Software & 3D Models available at: www.temposonics.com

Data Sheet

GLOSSARY

C

CIP Sync

Synchronization services in CIP (Common Industrial Protcol) provide the increased control coordination to achieve real-time synchronization between distributed devices and systems. CIP Sync™ is compliant with IEEE-1588™ standard and allows synchronization accuracy between two devices of fewer than 100 nanoseconds.

D

DLR

The Device Level Ring (DLR) protocol provides a means for detecting, managing and recovering from faults in a ring-based network.

E

EDS

The properties and functions of an EtherNet/IP™ device are described in an EDS file (Electronic Data Sheet). The XML-based EDS file contains all relevant data that are important for the implementation of the device in the controller as well as for data exchange during operation. The EDS file of the R-Series V EtherNet/IP™ is available on the homepage www.temposonics.com.

EtherNet/IP™

EtherNet/IP™ (Ethernet Industrial Protocol) is an Industrial Ethernet interface and is managed by the Open DeviceNet Vendor Association (ODVA). The R-Series V EtherNet/IP™ and its corresponding EDS file are certitified by the ODVA.

Internal Linearization

The internal linearization offers an improved linearity for an overall higher accuracy of the position measurement. The internal linearization is set for the sensor during production

M

Measuring Direction

When moving the position magnet, the position and velocity values increase in the measuring direction.

- Forward: Values increasing from sensor electronics housing to rod end/profile end
- Reverse: Values decreasing from sensor electronics housing to rod end/profile end

Multi-position measurement

During the measurement cycle, the positions of every magnet on the sensor are simultaneously reported. The velocity is continuously calculated based on these changing position values as the magnets are moved.



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