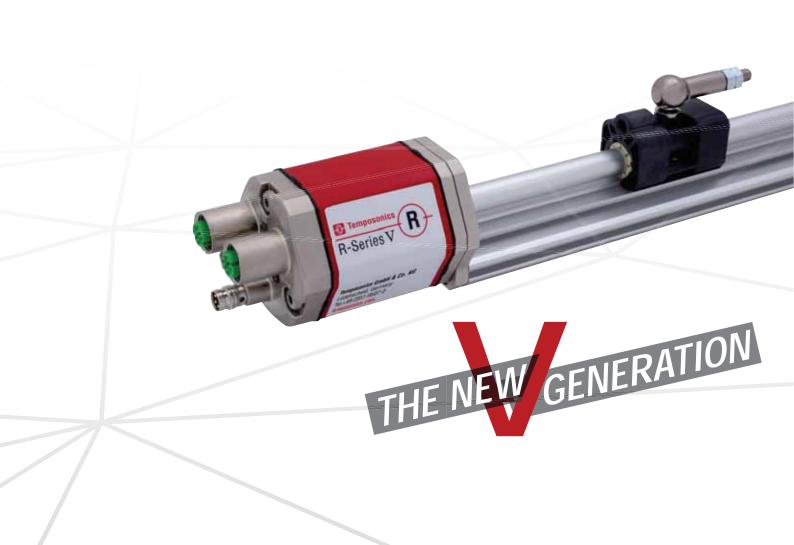


# **Data Sheet**

# **R-Series V RP5 POWERLINK**

Magnetostrictive Linear Position Sensors

- Minimum position resolution 0.5 µm
- Position and velocity measurements for up to 30 magnets
- Field adjustments and diagnostics using the new TempoLink smart assistant



#### MEASURING TECHNOLOGY

The absolute, linear position sensors provided by Temposonics rely on the company's proprietary magnetostrictive technology, which can determine position with a high level of precision and robustness. Each Temposonics position sensor consists of a ferromagnetic waveguide, a position magnet, a strain pulse converter and supporting electronics. The magnet, connected to the object in motion in the application, generates a magnetic field at its location on the waveguide. A short current pulse is applied to the waveguide. This creates a momentary radial magnetic field and torsional strain on the waveguide. The momentary interaction of the magnetic fields releases a torsional strain pulse that propagates the length of the waveguide. When the ultrasonic wave reaches the end of the waveguide it is converted into an electrical signal. Since the speed of the ultrasonic wave in the waveguide is precisely known, the time required to receive the return signal can be converted into a linear position measurement with both high accuracy and repeatability.

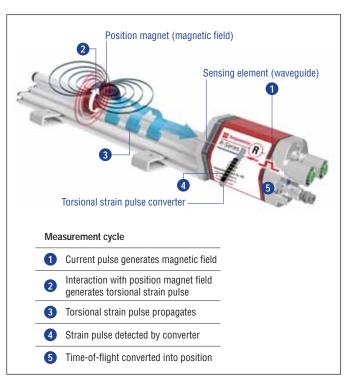


Fig. 1: Time-of-flight based magnetostrictive position sensing principle

## **R-SERIES V POWERLINK**

Temposonics® R-Series V brings very powerful sensor performance to meet the many demands of your application. The R-Series V is the long term solution for harsh environments that have high levels of shock and vibration. The sensor is equipped with POWERLINK V2 and supports a minimum cycle time of 250 µs. In time-critical applications, the linear extrapolation can be activated. This offers a cycle time of 200 µs for every sensor stroke length. The measurement of the sensor can be synchronized to the polling cycle of the controller. Temposonics® R-Series V sensors are available with internal linearization which offers improved linearity for overall higher accuracy of the position measurement values. In addition to the measured position value via the POWERLINK protocol further data about the current sensor status, such like the total distance travelled, the internal temperature and the total operating hours, can be displayed for diagnostic purposes.

With many outstanding features the R-Series V sensors are fit for a very broad range of applications.

## TempoLink® SMART ASSISTANT

The TempoLink® smart assistant is an accessory for the R-Series V family of sensors that supports setup and diagnostics. Depending on the sensor protocol it enables the adjustment of parameters like measurement direction, resolution and filter settings. For diagnostics and analysis of operational data the R-Series V sensors continuously track values such as total distance traveled by the positon magnet, internal temperature of the sensor and the quality of the position signal. This additional information can be read out via TempoLink® smart assistant even while the sensor remains operational in the application. TempoLink® smart assistant is connected to the sensor via the power connection, which now adds bidirectional communication for setup and diagnostics. The TempoLink® smart assistant is operated using a graphical user-interface that will be displayed on your smartphone, tablet, laptop or PC. Just connect your Wi-Fi-enabled device to TempoLink® Wi-Fi access point and go to the website URL for the user-interface.



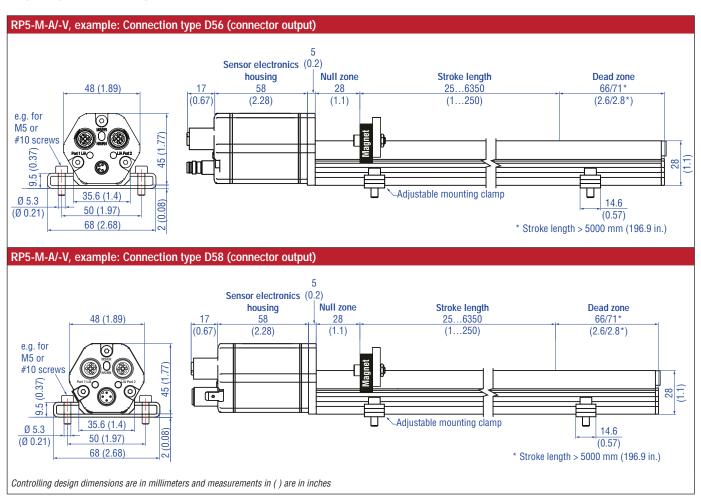
Fig. 2: R-Series V sensor with TempoLink® smart assistant

## **TECHNICAL DATA**

Outnut											
Output Interface	Ethernet DOWEDLINK										
	Ethernet POWERLINK										
Data protocol	POWERLINK V2 Position, velocity/option: Simultaneous multi-position and multi-velocity measurements up to 30 magnets										
Measured value	Position, velocity/option	n: Simultaneous r	nuiti-position and	multi-velocity m	neasurements up	to 30 magnets					
Measurement parameters											
Resolution: Position	0.5100 µm (selectable)										
Cycle time <sup>1</sup>	Stroke length ≤ 50 mm ≤ 715 mm ≤ 2000 mm ≤ 4675 mm ≤ 6350 mm Cycle time 250 $\mu$ s 1000 $\mu$ s 2000 $\mu$ s 2800 $\mu$ s										
Linearity deviation <sup>2</sup>	Stroke length   ≤ 500 mm   > 500 mm										
Emounty deviation	Linearity deviation $\leq \pm 50  \mu \text{m}$ $< 0.01  \%  \text{F.S.}$										
	Optional internal linearization: Linearity tolerance (applies for the first magnet for multi-position measurement) Stroke length $ 25300 \text{ mm}  300600 \text{ mm}  6001200 \text{ mm}  12003000 \text{ mm}  30005000 \text{ mm}  50006350 \text{ mm} $ typical $\pm 15 \mu\text{m} $ $\pm 20 \mu\text{m} $ $\pm 25 \mu\text{m} $ $\pm 45 \mu\text{m} $ $\pm 85 \mu\text{m} $ $\pm 95 \mu\text{m}$ maximum $\pm 25 \mu\text{m} $ $\pm 30 \mu\text{m} $ $\pm 50 \mu\text{m} $ $\pm 90 \mu\text{m} $ $\pm 150 \mu\text{m} $ $\pm 190 \mu\text{m} $										
Repeatability	< ±0.001 % F.S. (minimum ±2.5 µm) typical										
Hysteresis	< 4 µm typical										
Temperature coefficient	< 15 ppm/K typical										
Operating conditions											
Operating temperature	-40+85 °C (-40+185 °F)										
Humidity	90 % relative humidity, no condensation										
Ingress protection	IP67 (connectors correctly fitted)										
Shock test	150 g/11 ms, IEC standard 60068-2-27										
Vibration test	30 g/102000 Hz, IEC standard 60068-2-6 (excluding resonant frequencies)										
EMC test	Electromagnetic emission according to EN 61000-6-3 Electromagnetic immunity according to EN 61000-6-2 The sensor meets the requirements of the EC directives and is marked with C €										
Magnet movement velocity	Magnet slider: Max. 10 m/s; U-magnet: Any; block magnet: Any										
Design / Material											
Sensor electronics housing	Aluminum (painted), zir	nc die cast									
Sensor profile	Aluminum										
Stroke length	256350 mm (1250	) in.)									
Mechanical mounting											
Mounting position	Any										
Mounting instruction											
Electrical connection											
Connection type	2 × M12 female connectors (D-coded), 1 × M8 male connector; 2 × M12 female connectors (D-coded), 1 × M12 male connector (A-coded)										
Operating voltage	+1230 VDC ±20 % (9.636 VDC)										
Power consumption	Less than 4 W typical										
Dielectric strength	500 VDC (DC ground to	machine ground	)								
Polarity protection	Up to -36 VDC										
Overvoltage protection	Up to 36 VDC										

<sup>1/</sup> Minimum cycle time for multi-position measurements (number of magnets  $\geq$  2): 400  $\mu s$  2/ With position magnet # 251 416-2

## **TECHNICAL DRAWING**



 $\textit{Fig. 3: Temposonics}^{\circ}~\textit{RP5}~\textit{with $U$-magnet}$ 

## **CONNECTOR WIRING**

D56		
Port 1 – Signal		
M12 female connector (D-coded)	Pin	Function
	1	Tx (+)
$4\bigcirc 2$	2	Rx (+)
3	3	Tx (-)
View on sensor	4	Rx (-)
Port 2 – Signal		
M12 female connector (D-coded)	Pin	Function
	1	Tx (+)
2 (4)	2	Rx (+)
1	3	Tx (-)
View on sensor	4	Rx (-)
Power supply		
M8 male connector	Pin	Function
	1	+1230 VDC (±20 %)
(0°)	2	Not connected
View on sensor	3	DC Ground (0 V)
VIEW UII SEIISUI	4	Not connected

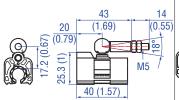
Fig. 4: Connector wiring D56

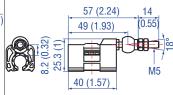
D58		
Port 1 – Signal		
M12 female connector (D-coded)	Pin	Function
	1	Tx (+)
$\overset{\cup}{4\bigcirc 2}$	2	Rx (+)
3	3	Tx (-)
View on sensor	4	Rx (-)
Port 2 – Signal		
M12 female connector (D-coded)	Pin	Function
	1	Tx (+)
$2\bigcirc 4$	2	Rx (+)
1	3	Tx (-)
View on sensor	4	Rx (-)
Power supply		
M12 male connector (A-coded)	Pin	Function
	1	+1230 VDC (±20 %)
(e o)	2	Not connected
	3	DC Ground (0 V)
View on sensor	4	Not connected

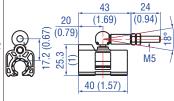
Fig. 5: Connector wiring D58

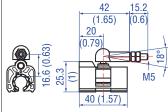
## FREQUENTLY ORDERED ACCESSORIES – Additional options available in our Accessories Guide 7 551444

#### Position magnets









Magnet slider S, joint at top Part no. 252 182

Material: GRP, magnet hard ferrite Weight: Approx. 35 g Operating temperature: -40...+85 °C (-40...+185 °F)

Magnet slider V, joint at front Part no. 252 184

Material: GRP, magnet hard ferrite Weight: Approx. 35 g Operating temperature: -40...+85 °C (-40...+185 °F)

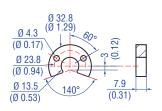
Magnet slider N longer ball-joint arm Part no. 252 183

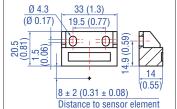
Material: GRP, magnet hard ferrite Weight: Approx. 35 g Operating temperature: -40...+85 °C (-40...+185 °F)

Magnet slider G, backlash free Part no. 253 421

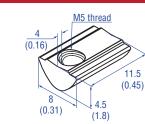
Material: GRP, magnet hard ferrite Weight: Approx. 25 g Operating temperature: -40...+85 °C (-40...+185 °F)

#### **Position magnets**





#### Mounting accessories 4 holes Ø 5.3 (Ø 0.21) 28 (1.1) 9 (0.35)



#### U-magnet OD33 Part no. 251416-2

Material: PA ferrite GF20 Weight: Approx. 11 g Surface pressure: Max. 40 N/mm<sup>2</sup> Fastening torque for M4 screws: 1 Nm Operating temperature: -40...+105 °C (-40...+221 °F)

Marked version for sensors with internal linearization: Part no. 254226

#### Block magnet L Part no. 403 448

magnet Weight: Approx. 20 g Fastening torque for M4 screws: 1 Nm Operating temperature:

This magnet may influence the sensor performance specifications for some

-40...+75 °C (-40...+167 °F)

applications.

## Mounting clamp Part no. 400 802

2 (0.08)-

Material: Plastic carrier with hard ferrite Material: Stainless steel (AISI 304)

50 (1.97)

68 (2.68)

Mounting clamp width:

14.6 (0.57)

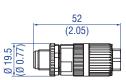
#### T-nut Part no. 401 602

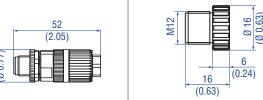
(0.37)

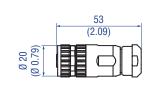
Fastening torque for M5 screw: 4.5 Nm

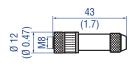
#### Cable connectors\* - Signal

#### Cable connectors\* - Power









M12 D-coded male connector (4 pin), straight Part no. 370 523

Material: Zinc nickel-plated Termination: Insulation-displacement Cable Ø: 5.5...7.2 mm (0.2...0.28 in.) Wire: 24 AWG - 22 AWG Operating temperature: -25...+85 °C (-13...+185 °F) Ingress protection: IP65 / IP67 (correctly fitted)

M12 connector end cap Part no. 370 537

Female connectors M12 should be covered by this protective cap Material: Brass nickel-plated Ingress protection: IP67 (correctly fitted) Fastening torque: 0.39...0.49 Nm

M12 A-coded female connector (4 pin/5 pin), straight Part no. 370 677

Material: GD-Zn, Ni Termination: Screw Contact insert: CuZn Cable Ø: 4...8 mm (0.16...0.31 in.) Wire: 1.5 mm<sup>2</sup> Operating temperature: −30...+85 °C (−22...+185 °F) Ingress protection: IP67 (correctly fitted) Fastening torque: 0.5 Nm Fastening torque: 0.6 Nm

M8 female connector (4 pin), straight Part no. 370 504

Material: CuZn nickel plated Termination: Solder Cable Ø: 3.5...5 mm (0.14...0.28 in.) Wire: 0.25 mm<sup>2</sup> Operating temperature: -40...+85 °C (-40...+185 °F) Ingress protection: IP67 (correctly fitted)

#### Programming kit

Fastening torque: 0.6 Nm

#### **Cables**









TempoLink® kit for Temposonics® R-Series V Part no. TL-1-0-EM08 (D56) Part no. TL-1-0-EM12 (D58)

- · Connect wirelessly via Wi-Fi enabled device or via USB with the diagnostic
- · Simple connectivity to the sensor via 24 VDC power line (permissible cable length: 30 m)
- · User friendly interface for mobile devices and desktop computers
- See data sheet "TempoLink® smart assistant" (document part no.: 552070) for further information

PUR signal cable Part no. 530 125

Material: PUR jacket; green Features: Cat 5, highly flexible, halogen free, suitable for drag chains, mostly oil Cable length: 5 m (16.4 ft) & flame resistant Cable Ø: 6.5 mm (0.26 in.) Cross section: 2 x 2 x 0.35 mm<sup>2</sup> (22 AWG) Operating temperature:

-20...+60 °C (-4...+140 °F)

Signal cable with M12 D-coded male connector (4 pin), straight - M12 D-coded, male connector (4 pin), straight Part no. 530 064

Material: PUR jacket; green Features: Cat 5e Cable Ø: 6.5 mm (0.26 in.) Ingress protection: IP65, IP67, IP68 (correctly fitted) Operating temperature: -30...+70 °C (-22...+158 °F)

Signal cable with M12 D-coded male connector (4 pin), straight - RJ45 male connector, straight Part no. 530 065

Material: PUR jacket; green Features: Cat 5e Cable length: 5 m (16.4 ft) Cable Ø: 6.5 mm (0.26 in.) Ingress protection M12 connector: IP67 (correctly fitted) Ingress protection RJ45 connector: IP20 (correctly fitted) Operating temperature: -30...+70 °C (-22...+158 °F)

Controlling design dimensions are in millimeters and measurements in ( ) are in inches

<sup>\*/</sup> Follow the manufacturer's mounting instructions

## **Cables**





PVC power cable Part no. 530 108 Power cable with M8 female connector (4 pin), straight – pigtail Part no. 530 066 (5 m (16.4 ft.)) Part no. 530 096 (10 m (32.8 ft.)) Part no. 530 093 (15 m (49.2 ft.))

Material: PVC jacket; gray Features: Shielded, flexible, mostly flame resistant Cable Ø: 4.9 mm (0.19 in.) Cross section:  $3 \times 0.34$  mm² Bending radius:  $10 \times D$ Operating temperature: -30...+80 °C (-22...+176 °F)

Material: PUR jacket; gray Features: Shielded Cable Ø: 5 mm (0.2 in.) Operating temperature: -40...+90 °C (-40...+194 °F)

#### **ORDER CODE**

1 2 3	4	5	6	7	8	9	10	11	12	13	14	15	16		18	19	20
R P 5										D	5		1	U	3		1
a	b	С			d			€	;		f		g		ŀ	1	

## a Sensor model

R P 5 Profile

#### b Design

- G Magnet slider backlash free (part no. 253 421), suitable for internal linearization
- L Block magnet L (part no. 403 448)
- M U-magnet OD33 (part no. 251 416-2), suitable for internal linearization
- N Magnet slider longer ball-jointed arm (part no. 252 183), suitable for internal linearization
- O No position magnet
- Magnet slider joint at top (part no. 252 182), suitable for internal linearization
- Magnet slider joint at front (part no. 252 184), suitable for internal linearization

#### c Mechanical options

- A Standard
- V Fluorelastomer seals for the sensor electronics housing

#### d Stroke length

X X X X M 0025...6350 mm

Standard stroke length (mm)	Ordering steps	
25 500 mm	25 mm	
5002500 mm	50 mm	
25005000 mm	100 mm	
50006350 mm	250 mm	

X X X X U 001.0...250.0 in.

Non-standard stroke lengths are available; must be encoded in 5 mm/0.1 in. increments.

## e Number of magnets

X X 01...30 position(s) (1...30 magnet(s))

#### f | Connection type

- D 5 6 2×M12 female connectors (D-coded), 1×M8 male connector
- D 5 8 2×M12 female connectors (D-coded), 1×M12 male connector (A-coded)

## g System

1 Standard

## h Output

- U 3 0 1 POWERLINK, position and velocity (1...30 position(s))
- U 3 1 1 POWERLINK, position and velocity, internal linearization (1...30 position(s))

#### NOTICE

- For RP5, the magnet selected in b "Design" is included in the scope of delivery. Specify the number of magnets for your application. For multi-position measurements with more than 1 magnet order the other magnets separately.
- The number of magnets is limited by the stroke length.

  The minimum allowed distance between magnets (i.e. front face of one to the front face of the next one) is 75 mm (3 in.).
- Use magnets of the same type for multi-position measurement, e.g. 2 × U-magnet (part no. 251 416-2).
- If the option for internal linearization (U311) in **h** "Output" is chosen, select a suitable magnet.

## **DELIVERY**



- Sensor
- Position magnet (not valid for RP5 with design »O«)
- 2 mounting clamps up to 1250 mm (50 in.) stroke length
- + 1 mounting clamp for each 500 mm (20 in.) additional stroke length

Accessories have to be ordered separately.

Manuals, Software & 3D Models available at: <a href="https://www.temposonics.com">www.temposonics.com</a>



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